Some Improvements of the Simulated Annealing Method for the Determination of Atmospheric Parameters from the Curve-of-Growth

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成長曲線からの大気パラメータの決定のための
疑似焼きなまし法のいくつかの改良点

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ABSTRACT

We made the three programs which modify the program of the Curve-of-Growth Analysis by the Simulated Annealing Method made by Yoshioka (2011), according to the suggestion made by Press et al. (1992). These programs determines the four variables, $\Delta x$, $\Delta y$, $\theta_0$, and $\log(\Delta a)$ as the best set of the four variables from the staring set of 5 points of the four variables, where $\Delta x$ is difference between an empirical curve-of-growth and a theoretical curve-of-growth in the direction parallel to the abscissa and $\Delta y$ is difference of the two curves in the direction parallel to the ordinate. The objective function is taken to be the variance of lines in the direction parallel to the abscissa of a curve-of-growth.

The effectiveness of these programs was tested by comparing the results by these programs with those by the program of the Downhill Simplex Method by Yoshioka and Kobayashi (2009) and by the program of the Simulated Annealing Method by Yoshioka (2011). The data used for the comparison are those for 86 lines of Fe I of HD167200. The following conclusions were drawn from the test.

1) Almost the same values of the best set of the four variables are obtained for the three programs.
2) The results depend on the $T_i$ parameter and the starting set of the four variables for all the three programs, where the $T_i$ parameter is the first value of the parameter which is used in the Simulated Annealing Method as that corresponding to temperature.
3) The results depend slightly or do not depend on the other parameters. Taking the smallest value of the objective function into account, the one of the three program seems to be the most robust programs among the three programs.
4) Compared with the programs of the Downhill Simplex Method and the Simulated Annealing Method, the three programs give the smallest value of the objective function which are smaller than that for the program of the Downhill Simplex Method and comparable to that for the program of the Simulated Annealing Method. The three program give the result with parameters smaller than that for the Simulated Annealing Method.
5) In case of reasonable values of the parameters and the starting set of the four variables, the three programs give the four variables, $\Delta \theta_0$, $\log(\Delta a)$, $\Delta x$, and $\Delta y$ within the errors of $\pm 0.03$, $\pm 0.10$, $\pm 0.04$ and $\pm 0.04$, respectively.
6) Although the above errors are small by the standards of the curve-of-growth analysis, it is still desirable to devise a algorithm to avoid converging to a local minimum before converging to the global minimum.

要 旨

われわれは、Yoshioka (2011) が作成した疑似焼きなまし法を適用して成長曲線から大気パラメータを求めるプログラムを、Press et al. (1992) の提案に従って改良する 3 つのプログラムを作成した。これらのプログラムは、$\Delta x$, $\Delta y$, $\theta_0$, and $\log(\Delta a)$ の 4 つの変数をこの変数の 5 つ初期値の組から求めるものである。なお、$\Delta x$ と同様に観測された成長曲線と理論成長曲線との相関の差を意味し、$\Delta y$ は両成長曲線の縦軸の差を意味する。ここで目的関数は、成長曲線

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上にプロットされた吸収線の横座標のちからりの分散値とした。

われわれは、これらのプログラムとYoshioka and Kobayashi（2009）が作成した成長曲線法のプログラムと
Yoshioka（2011）が作成した擬似焼きなまし法のプログラムの結果を比較することにより、これらのプログラムの
有効性を調べた。比較に使われたデータは、HD187203のFe Iの吸収線86本である。そして、次の結果を得た。
1) 3つのプログラムは、最小2つの変数の組み合わせとして、ほとんど同じ値を与える。
2) 3つのプログラムとも、パラメータの値と2つの変数の初期値に結果は依存する。ここで、パラメータTnは擬
似焼きなまし法で、温度に対応するパラメータである。
3) 結果は、残りのパラメータに依存しないか、ほとんど依存しない。評価関数の値を考慮すると、3つのプログラ
ムの中の1つが最も影響の受けにくいプログラムであるように思われる。
4) 減少シンプレックス法のプログラムと比べて、3つのプログラムはより小さい評価関数の値を与え、凝似焼きな
まし法のプログラムと比べて、同程度の値を与える。凝似焼きなまし法のプログラムと比べて、3つのプログラ
ムはより少ない数のパラメータで足りる。
5) パラメータと4つの変数の初期値を適切に選ぶならば、4つの変数$\Delta \theta_n, \log_2 a, \Delta x, \text{and } \Delta y$の最適値は、次の誤差範囲で決まる。
   $\pm 0.00, \pm 0.10, \pm 0.04, \pm 0.04$。

6) 5)の誤差は、成長曲線解析法の基準からいえば、小さいが、局所の最小値に限らないで大局的最小値に達するた
めに、さらにプログラムを改良する余地が残されている。

I. Introduction

A curve-of-growth analysis is one of the methods which are used for the analysis of stellar photospheres. The other method which is mainly used is a model atmosphere analysis. Since detailed distribution of physical quantities such as temperature and pressure and so on are taken into account in a model atmosphere analysis, it is called a fine analysis. It is used when accurate observational data are available and the nature of stellar photosphere is known to a good approximation.

A curve-of-growth analysis is usually used when accurate observational data are not available or there is not enough knowledge about the nature of a stellar photosphere. In this analysis, one-layer approximation is made, i.e., it is assumed that there exists a specific value for a physical quantity of the photosphere such as temperature and pressure.

A curve-of-growth is a graphical representation of the relation between the logarithm of an equivalent width of an absorption line, $\log_2 W$, and the logarithm of a number density of absorption atoms, $N$, times an oscillator strength, $f$, times a statistical weight, $g$, $\log_2 g N$. The equivalent width of an absorption line is the width of the rectangular profile for which the height is equal to the continuum level near the absorption line. The equivalent width divided by the wavelength of the absorption line, $\lambda$, $W/\lambda$ is often used instead of $W$, and some multiplicative factor $C$, is often added to $g N$. We obtain by this method the representative quantities of a photosphere, for example, electron pressure, gas pressure, micro-turbulent velocity, ionization temperature, and excitation temperature, $T_n$, together with chemical composition. This analysis is also called coarse analysis.

In cases where accurate values for oscillator strength are not known, the values of the ordinate of the curve-of-growth, $\log_2 X$, for a standard star are plotted instead of $\log_2 g N$ or $\log_2 g N / C$. The standard star is the star for which the physical quantities and the chemical composition of the photosphere are already obtained. In this case, the relative values to the standard star for the physical quantities and the chemical composition are obtained instead of the absolute values. This analysis is called a differential curve-of-growth analysis or a differential coarse analysis.

II. Procedure by Using a Computer Done to Date

The curve-of-growth analysis has conventionally been done by eye measure. There is a fear that the results obtained by eye measure depend on the subjectivity of an analyzer. Moreover, an objective estimate of an error cannot been made by eye measure. The curve-of-growth by using a computer have been applied in order to overcome the above weak points.

For example, Tech (1971)2 has made a differential curve-of-growth analysis for Ba II star $\zeta$ Cap, using $\epsilon$ Vir as a standard star, he determined the differential reciprocal temperature, $\Delta \theta_n (\theta_n = 5040/T_n)$ relative to the standard star by the minimum–sigma method, using a computer. Powell (1971)2 has made a computer program for a differential curve-of-growth analysis of solar-type stars.

The detailed explanations for these methods are described in the original papers and in the paper by Yoshioka and Kobayashi (2009)12. We describe in this
paper an outline and strong and weak points of these methods.

In the minimum–sigma method, several values of \( \Delta \theta_m \) are chosen and the abscissa of curve–of–growth, \( \log_{10} X_m \) is taken according to the following expression,

\[
\log_{10} X_m = \log_{10}^\prime X - \Delta \theta_m \chi,
\]

(1)

where \( \log_{10} X \) is the abscissa of a curve–of–growth of a standard star and \( \chi \) is the excitation potential of the lower level of an absorption line. Then, a theoretical curve–of–growth is fitted to the above empirical curve–of–growth, and the standard deviation \( \sigma \) of the empirical curve–of–growth from the theoretical curve–of–growth in the direction parallel to the abscissa is calculated. By repeating the above procedure for several values \( \Delta \theta_m \), a correlation between \( \sigma \) and \( \Delta \theta_m \) is obtained. The adopted value of \( \Delta \theta_m \) is taken to be the value for which \( \sigma \) takes the minimum value. Using this value of \( \Delta \theta_m \), the empirical curve–of–growth is constructed by plotting for each line \( \log_{10} X_m \) along the abscissa and \( \log_{10} W/\lambda \) along the ordinate. This empirical curve–of–growth is used to obtain the other representative quantities of a photosphere.

The strong points of this procedure, which is the reversal of the weak points of the conventional procedure, are as follows: 1) Each line is treated separately and separate weight can be applied to each line; 2) Correct excitation potential rather than mean values of excitation potential are taken into account; 3) It gives dispassionately reproducible results and objective estimates of error. On the other hand, this procedure has the following weak points: 1) Great care must be exercised in assuring that no wide discordant lines are used; 2) Since lines on the flat part or on the damping part of a curve–of–growth will dominate the value of \( \sigma \) and mask the variation due to the variation of \( \Delta \theta_m \), such lines are excluded in this analysis, which brings about ambiguity to the results; 3) There is not a guarantee that a mean curve–of–growth from which the value \( \sigma \) is calculated really represents the distribution of points adequately.

According to the computer program made by Powell (1971)\(^7\) the \( \Delta \theta_m \) value and the vertical and the horizontal shifts which fit an empirical curve–of–growth to a theoretical one are first determined, and then the shape of the theoretical curve, i.e. the damping parameter of the curve is determined. In the determination of the \( \Delta \theta_m \) value and the vertical and the horizontal shifts, only the lines which are on the linear part or on the knee of the flat part of the curve–of–growth are used, because the \( \Delta \theta_m \) value which is determined from these lines depends only slightly on the shape of the theoretical curve and is not affected much by the vertical shift adopted in the fitting. The determination of the \( \Delta \theta_m \) value and the vertical and the horizontal shifts is done in the following iterative way. First, the empirical curve–of–growth is constructed adopting the \( \Delta \theta_m \) value. Secondly, the empirical curve is fitted to the theoretical curve. Thirdly, the value of \( \log_{10} X \) corresponding to \( \log_{10} W/\lambda \) for the star analyzed is read off for each absorption line from this theoretical curve. Lastly, a new \( \Delta \theta_m \) value is found from a least squares solution to the relation,

\[
[X] = [A] - \Delta \theta_m \chi,
\]

(2)

where square bracket represents the logarithmic difference of the denoted quantity between the star analyzed and the standard star \( A \) is the number ratio of a relevant element and to hydrogen uncorrected for ionization. The above iterative process is repeated until a difference between successive estimate of \( \Delta \theta_m \) becomes less than the convergence tolerance ( \( = 0.005 \)).

Adopting the values of \( \Delta \theta_m \), and of the vertical and the horizontal shifts thus determined, the final value of damping parameter of the curve–of–growth is determined by obtaining the best fit of the empirical curve on the condition for a least–squares fit in a direction parallel to the ordinate. If the difference between this value of damping parameter and the previous value of the theoretical curve which is used to determine the \( \Delta \theta_m \) value and the vertical and the horizontal shifts is greater than 1, the whole process is repeated using the new value of damping parameter.

The strong points of this procedure are the same as described for the minimum–sigma method. The weak points of this procedure also are the same as the minimum–sigma method, except for the third point. There are, however, other two weak points: 1) There is a fear of divergence in the iterative process; 2) The determination of the values of \( \Delta \theta_m \), and of the vertical and the horizontal shifts is done on the condition for a least–squares fit in a direction parallel to the abscissa, while the determination of the value of damping parameter is done on the condition for a least–squares fit in a direction parallel to the ordinate, which lacks consistency.

Yoshioka (1987)\(^8\) developed a new procedure. In the new procedure, the determination of the four values of \( \Delta \theta_m \), damping parameter, and vertical and horizontal shifts is done in the following way. First, the value of damping parameter is given for a theoretical curve–of–growth. Secondary, the theoretical curve is fitted to the empirical curve and the values \( \Delta \theta_m \), and horizontal shift are determined as least–squares solution in the direction parallel to abscissa for various values of vertical shift. Thirdly, the value of vertical shift and the corresponding values of \( \Delta \theta_m \), and horizontal shift which gives a minimum value of standard devia-
tion, \( \sigma_{max} \), of the \( \Delta \theta_n \) value are selected. The above process is repeated for various values of damping parameter, and the four values of \( \Delta \theta_n \), damping parameter, and vertical and horizontal shifts on which the \( \sigma_{max} \) value takes the minimum value are adopted as the final values. In the above process, a gradient of the theoretical curve-of-growth for the ordinate of a line is taken into account as a weight for the least-squares solution so that the lines on the linear and damping parts of the curve-of-growth are given heavier weight than those on the flat part of the curve, because the latter lines give a larger difference between theoretical and empirical curve-of-growth for the same value of error in the ordinate.

The strong points of this procedure are the same as those of the minimum-sigma method and of the procedure by Powell (1971)\(^2\). The weak points of both of these procedures, i.e., the ambiguity in the use of lines and the inconsistency in the use of curve-of-growth are overcome in the procedure by Yoshioka (1987)\(^4\), because this procedure uses all the lines which belong to those on the flat and damping parts of curve-of-growth and the same theoretical curve-of-growth are used for the determination of the four values.

### III. Procedure by Using the Downhill Simplex Method

In the procedure by Yoshioka (1987)\(^4\), as well as in the other procedure described above, the four values of \( \Delta \theta_n \), damping parameter, and vertical and horizontal shifts are determined through some stages. Yoshioka (2008)\(^5\) developed a new procedure using the downhill simplex Method. The procedure above described can be regarded as one of optimization problem where the optimal solution is the set of four variables, \( \Delta \theta_n \), damping parameter, and vertical and horizontal shifts. The objective function in our problem which is minimized by the optimal solution is selected according to the criterion of agreement between the empirical curve-of-growth and the theoretical one. The variance of absorption lines in the curve-of-growth in the direction parallel to the ordinate is selected as the objective function in the procedure by Powell (1971)\(^2\). On the other hand, the variance of lines in the curve-of-growth in the direction parallel to the abscissa is selected as the objective function in the procedure of the minimum-sigma method and that by Yoshioka (1987)\(^4\). Yoshioka and Kobayashi (2009)\(^5\) made a program which solves this optimization problem by the downhill simplex method due to Nelder and Mead (1965)\(^5\) (hereafter referred to as DSM).

The detailed explanations of DSM is described in the paper by Yoshioka and Kobayashi (2009)\(^3\). We describe in this paper an outline of this method. In DSM, a simplex is the geometric figure consisting in N dimensions (N is the number of independent variables, and in our case, N is equal to 4) of N + 1 points (or vertices) and of all of their interconnecting line segments and of polygonal faces. In DSM, the determination of solution is done in the following iterative way. It starts with N + 1 points which define an initial simplex. The point of a simplex where the objective function takes the largest value, which is called the highest point, takes a series of the following four steps: 1) a reflection away from the highest point; 2) a reflection and expansion away from the highest point; 3) a contraction along one dimension from the highest point; 4) a contraction along all dimensions towards the lowest point. In the above steps, the lowest point is the point where the objective function takes the smallest value. The above steps repeat and they terminate when the vector distance moved in one of those steps is fractionally smaller in magnitude than some tolerance or, alternatively, the decrease in the objective function is fractionally smaller than some tolerance.

Yoshioka and Kobayashi (2009)\(^3\) obtained the four variables using the program made by him which determines these values by DSM as the values when the above steps terminate, whose values are hereafter called the best values. As described by Yoshioka and Kobayashi (2009)\(^3\), it was confirmed that this program is effective for the determination of the four values, i.e., in comparison with the program by Yoshioka (1987)\(^4\), this program reaches the best values in quite short steps and in quite short time. On the other hand, the following problems resulted.

1) The best values depend on the starting set of the four values. According to the starting set of the values, the four values of \( \Delta \theta_n \), damping parameter, \( \log_{10} \alpha \), horizontal shift, \( \Delta x \), and vertical shift, \( \Delta y \), differ by \( \pm 0.01, \pm 0.09, \pm 0.05, \pm 0.06 \), respectively.

2) There are some starting sets of the four values which does not converge to the best values in the case where the tolerance of the decrease in the objective function for the termination of the iterative process is smaller than some value (in this case which is equal to 0.00007).

### IV. Procedure by Using the Simulated Annealing Method

In the following paper by Yoshioka (2011)\(^6\), we
have made the program which avoids the above problems for DSM. The objective function for the above determination of the four variables has many local minima, which causes the above problems. The simulated annealing method (hereafter referred to as SAM) is a method that is suitable for minimization problems of large scale where a desired global minimum is hidden among many local minima.

The heart of SAM is an analogy with the way that liquids freeze and crystallize. At high temperatures, the molecules of a liquid move freely due to the thermal motion. If the liquid is cooled slowly, thermal motion quiets down. The molecules form a crystal that is ordered over the distance which is long compared with the size of the molecules. This crystal is at the state of minimum energy for this system. For slowly cooled systems, nature is able to find this minimum energy state. If it is cooled quickly, it does not reach this state, but it ends up in a polycrystalline or amorphous state which has somewhat higher energy. The essence of this process is slow cooling, which requires ample time for redistribution of the molecules as they lose mobility. This is the technical definition of annealing, and it is essential for ensuring that a low energy state is achieved.

So nature’s minimization algorithms is based on the following procedure. The following Boltzmann probability distribution,

$$P(E) \propto \exp(-E/kT)$$

(3)

indicates that a system in thermal equilibrium at temperature $T$ has its energy probabilistically distributed among all different states with energy $E$ according to the expression (3), where $P$ is the probability of distribution. According to the expression (3), there is a chance of a system being in a high state. Therefore, there is a corresponding chance for the system to get out of a local minimum in favor of finding a better and more global one. The system sometimes goes uphill of energy levels as well as downhill. The lower the temperature, the less likely is a significant uphill excursion.

SAM is a procedure for minimization which simulates the above procedure by nature. Metropolis and coworkers first made the program of SAM for combinatorial minimization which is known as the Metropolis algorithm. Afterwards, the programs of SAM for minimization with continuous variables were made by several researchers. We adopted the procedure by Press et al. (1992)⁶, which uses a modification of DSM.

In our program, a simplex of $N+1$ points moves in the same way as in DSM, i.e., which reflects or expands or contracts. A positive, logarithmically distributed random variable which is proportional to the temperature $T$ is added to the four variables associated with every vertex of the simplex, and a similar random variable is subtracted from the four variables of every new point which is tried as a replacement point. This procedure almost accepts a downhill step, but sometimes accepts an uphill one. In the limit where $T$ comes close to zero, this algorithm reduces DSM and converges to a local minimum. At a finite value of $T$, the simplex expands to a scale which approximates the size of the region that can be reached at this temperature, and then it executes a stochastic Brownian motion within that region, sampling new random points. The efficiency with which a region is explored is independent of the distribution of the value of the objective function around the region sampled, whereas the efficiency is dependent of the distribution in the majority of the other minimization method.

There are many annealing schedules which resemble the annealing by nature. Success or failure is often determined by the choice of annealing schedule. The schedule adopted by Yoshioka (2011)⁷ is as follows.

[1] A starting points of a simplex in 4 dimension comprising of 5 points is given. Then, the $F$ values corresponding to each point are calculated, and the smallest $F$ value, $F_n$, is determined, where $F$ value is the value of the objective function.

[2] A series of random movements of a simplex including contraction and expansion is executed according to a starting $T$ value. Then, the smallest $F$ value, $F_n$, is determined in the $F$ values which are obtained in the above series of movements.

[3] Next series of movements is executed and the corresponding $F_n$ value is obtained. In the case where this $F_n$ value is smaller than that obtained with the former step, the $T$ value is multiplied or divided by the SS value which is smaller than 1 and is close to 1. In the above operation, the multiplication is executed when in the former step the multiplication is executed, and the division is executed when in the former step the division is executed. Then, we go to the step [2]. In the case where this $F_n$ value is larger than that obtained with the former step, we go to the step [4].

[4] In the case where this $F_n$ value is smaller than $F_n$ value, the $F_n$ value of the former step is adopted. And the corresponding four variables is adopted as the best values. In the case where this $F_n$ value is larger than $F_n$ value, the $T$ value is multiplied or divided by the SSS value which is much smaller than 1. In the above operation, the multiplication is executed when in the former step the division is executed, and the division is executed.
when in the former step the multiplication is executed. Then we go to the step [4].

We tested our program by comparing the results of our program with those of the program by Yoshioka (1987)⁶ and of the program by Yoshioka (2011)⁷. The data used for the comparison is that for Fe I lines of HD187203 which is a supergiant with F8 type. The number of Fe I lines is equal to 86.

An absolute curve-of-growth analysis is done for the above data with the program by Yoshioka (1987)⁶ and the following set of the four variables $\Delta x$, $\Delta y$, $\theta_a$ (instead of $\Delta \theta_a$ in the case of an absolute curve-of-growth analysis) and $\log_{e}2a$ is obtained; $\Delta x = -3.075$, $\Delta y = 4.63$, $\theta_a = 1.02$, and $\log_{e}2a = -1.85$. The corresponding $F$ value is equal to 2.435970256.

On the other hand, we obtained by the program for DSM by Yoshioka and Kobayashi (2008)⁸ the following best set of the four variables; $\Delta x = -3.034$, $\Delta y = 4.67$, $\theta_a = 1.02$, and $\log_{e}2a = -1.81$, which is obtained for the same starting set as ①. The corresponding $F$ value is equal to 2.45371879. The above results are obtained for the following parameters; $ftol = 0.05$, $IITER = 20$, $TEMPTR = 0.0101$, $SS = 0.99$, $SSS = 0.01$, $IIDUM = -2$, and $NM = 10$, where $IITER$ is the maximum execution number of iteration for the satisfaction of $ftol$ value; $TEMPTR$ is the starting $T$ value; $IIDUM$ is a parameter for the program generating random number; $NM$ is the maximum number of iteration described in the former section. The above results depend not only on the above parameters but also on the starting set of the four variables. For example, the following best set of the four variables is obtained; $\Delta x = -3.032$, $\Delta y = 4.66$, $\theta_a = 1.02$, and $\log_{e}2a = -1.81$, for the following parameters; $ftol = 0.05$, $IITER = 20$, $TEMPTR = 0.001$, $SS = 0.99$, $SSS = 0.01$, $IIDUM = -1$, and $NM = 10$. This result is obtained for the starting set ②, $\Delta x = -2.90 - 0.05$, $\Delta y = 4.80 - 0.05$, $\theta_a = 1.60 - 0.20i$, and $\log_{e}2a = -2.40 + 0.20i$. The corresponding $F$ value is equal to 2.439946313 which is the smallest in the $F$ values obtained by our program for SAM.

V. Modifications to the Simulated Annealing Method

We have modified the program by Yoshioka (2011)⁷, according to the suggestion made by Press et al. (1992)⁹. Press et al. (1992)⁹ suggests that there are three modes which reduce the $T$ value sufficiently slowly. The first of the modes, which hereafter is called the mode $A$, is as follows. The $T$ value is reduced to $(1 - \varepsilon)$ $T$ value after every $m$ moves. The optimal $\varepsilon/m$ value depends on the situation where the program is applied. The second mode, which hereafter is called the mode $B$, is as follows. The $T$ value is reduced to $T_{0} (1 - k/K)^{m}$ after every $m$ moves, where $T_{0}$ is the initial $T$ value; $k$ is the cumulative number of moves thus far; $K$ is the total number of moves which is budgeted in advance; $\alpha$ is the constant, say, 1, 2, or 4. The optimal value of $\alpha$ depends on the situation where the program is applied. The third mode, which hereafter is called the mode $C$, is as follows. After every $m$ moves, the $T$ value is reduced to $T_{1} (1 - F_{i})$, where $\beta$ is constant of order 1; $F_{i}$ is the smallest value of the objective function currently represented in the simplex; $F_{i}$ is the smallest value of the objective function ever encountered. The above reduction is made under the restriction that $T$ does not reduce by more than some fraction $\gamma$ at a time. The optimal values of $\beta$ and $\gamma$ depend on the situation where the program is applied.

We have made the programs which adopted the above modes. Hereafter, we call these programs, the program SAM, SAMB, and SAMC, for the program which adopt the mode $A$, $B$, and $C$, respectively. We have applied the programs to the data, which were used for the comparison by Yoshioka and Kobayashi (2009)⁸ and by Yoshioka (2011)⁷ i.e. that for Fe I lines of HD187203 which is a supergiant with F8 type.

The following results are obtained for the program SAM. The smallest $F$ value of 2.441651618 is obtained for the following parameters; $T_{0} = 0.06$, $\varepsilon = 0.8$, and $m = 10$. The corresponding best set of the four variables is as follows; $\Delta x = -3.046$, $\Delta y = 4.65$, $\theta_a = 1.02$, and $\log_{e}2a = -1.85$. This result is obtained for the starting set ②. The results do not depend on the parameter $\varepsilon$ nor $m$. On the other hand, they depend on the parameter $T_{0}$. For example, the smallest $F$ value of 2.441785862 and of 2.540081172 are obtained for the $T_{0}$ parameter of 0.05 and 0.07, respectively. The corresponding best set of the four variables is as follows; $\Delta x = -3.046$, $\Delta y = 4.65$, $\theta_a = 1.02$, and $\log_{e}2a = -1.85$ and $\Delta x = -3.044$, $\Delta y = 4.66$, $\theta_a = 1.02$, and $\log_{e}2a = -1.78$, respectively. The results also depend
on the starting set of the four variables. For example, the smallest $F$ value of 2.53555494 is obtained for the starting set ①. This result is obtained for the the $T_c$ parameter of 0.06. The corresponding best set of the four variables is as follows: $\Delta x = -3.034$, $\Delta y = 4.67$, $\theta_a = 1.02$, and $\log_2 2a = -1.80$. The above smallest $F$ value is smaller than those for the $T_c$ parameter of 0.05 and 0.07, as for the starting set ②.

The following results are obtained for the program SAMB. The smallest $F$ value of 2.441544520 is obtained for the following parameters; $T_c = 0.008$, $k = 10$, $K = 300$, and $a = 2$. The corresponding best set of the four variables is as follows: $\Delta x = -3.046$, $\Delta y = 4.65$, $\theta_a = 1.02$, and $\log_2 2a = -1.81$. This result is obtained for the starting set ②. The results depend on the parameter $T_c$. For example, the smallest $F$ value of 2.441023899 and of 2.441042864 are obtained for the $T_c$ parameter of 0.002 and 0.004, respectively. The corresponding best sets of the four variables are the same as that for the above set. The results also depend on the starting set of the four variables. For example, the smallest $F$ value of 2.453532079 is obtained for the starting set ①. This result is obtained for the following Parameters; $T_c = 0.005$, $\beta = 1$, $\gamma = 0.8$, and $m = 400$. The corresponding best set of the four variables is as follows: $\Delta x = -3.034$, $\Delta y = 4.67$, $\theta_a = 1.02$, and $\log_2 2a = -1.81$. The results do not depend on the parameters $\beta$ and $\gamma$. The results depend on the $m$ parameter. But, they depend this parameter, only when the process does not converge, and after the convergence the results do not depend on this parameter. The results do not depend on the value of $\text{itol}$, neither.

VI. Conclusions and Discussion

The following conclusions are drawn from the above results.

1) Almost the same values of the best set of the four variables are obtained for the three programs, i.e., the program SAMA, SAMB, and SAMC for the parameters which give the smallest $F$ value. The smallest $F$ value are 2.441651618, 2.441544520, and 2.441021568 for the program SAMA, SAMB, and SAMC, respectively. The corresponding best sets of the three variables are the same for the three programs, i.e., they are as follows: $\Delta x = -3.046$, $\Delta y = 4.65$, $\theta_a = 1.02$. The $\log_2 2a$ values differ slightly, i.e., they are $-1.85$, $-1.81$, and $-1.80$, for the program SAMA, SAMB, and SAMC, respectively.

2) The results depend on the $T_c$ parameter and the starting set of the four variables for all the three programs. The above results of 1) were obtained for the $T_c$ values of 0.06, 0.008, and 0.003 for the program SAMA, SAMB, and SAMC, respectively. And the above results are obtained for the starting set ②. Except for the $\log_2 2a$ variable, the best set of the other three variables hardly depend on the $T_c$ parameter. On the other hand, both the $\log_2 2a$ and $\Delta x$ variables depend on the starting set of the four variables. Especially, the $\theta_a$ variable depend on neither the $T_c$ parameter nor the starting set of the four variables.

3) The result depends slightly on the parameters of $k$, $K$, and $a$ for the program SAMB, though the
best set of the four variables hardly depends on the above three parameters. On the other hand, the results do not depend on the other parameters, i.e., the $\varepsilon$ and $m$ parameters for the program SAMA, and the $\beta$ and $\gamma$ parameters for the program SAMC. Taking the smallest $F$ value into account, the program SAMC seems to be the most robust programs among the three programs.

4) Compared with the program DSM and SAM, the three programs give the smallest $F$ value which are smaller than that for the DSM and comparable to that for program SAM. The three program give the result with parameters smaller than that for the program SAM.

5) In case of reasonable values of the parameters and the starting set of the four variables, the three programs give the four variables, $\Delta \theta$, $\log e \Delta x$, $\Delta x$, and $\Delta y$ within the errors of $\pm 0.00$, $\pm 0.10$, $\pm 0.04$ and $\pm 0.04$, respectively.

6) Although the above errors are small by the standards of the curve-of-growth analysis, it is still desirable to devise a algorithm to avoid converging in a local minimum before converging to the global minimum.

References


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